

# Spectral Theorem (HW #7)

This material is in Section 6.4 of the 5th edition of your textbook.

This section continues our study of  $A^T A$ . We have already seen how  $A^T A$  helps find projections and how  $A^T C A$  is used to solve a circuit. Both of these matrices are symmetric and this section is about symmetric matrices.

**The Spectral Theorem** says that if  $A$  is an  $n \times n$  symmetric matrix with real entries, then

- 1) the eigenvalues of  $A$  are real;
- 2) the eigenspaces are orthogonal to each other;
- 3)  $A$  is complete: if  $\lambda$  is a multiple eigenvalue  $k$  times, then the corresponding eigenspace has dimension  $k$ ;  $A$  has no defect.

Diagonalize  $A = \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$ . Use an orthonormal basis for  $X$ . You might have to use Gram-Schmidt for the repeated eigenvalues.

Now use the diagonalization above and write  $A = \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$  in rank-1 form  $A = \sum_{i=1}^n \lambda_i \vec{q}_i \vec{q}_i^T$ . Each term in this form represents one "color" of a "rainbow" and makes a spectrum for  $A$ . We tend to order the eigenvalues from largest to smallest (though some applications prefer ascending order instead.)

Engineers often call the Spectral Theorem the **Principal Axis Theorem** because of this rank-1 decomposition. To understand why, we need to review ellipses:  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$  is the standard form for an ellipse centered at the origin with principal axes that are the  $y = 0$  and  $x = 0$  with "half-lengths" equal to  $a$  and  $b$  respectively.

Find the principal axes and half-lengths of the rotated ellipse  $3x^2 - 2xy + 3y^2 = 1$ ; as a start, notice that  $3x^2 - 2xy + 3y^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 3 & -1 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ ; then the square roots of the eigenvalues will be the reciprocals of the half-lengths and the corresponding eigenvectors the principal axes. To see why, diagonalize the symmetric matrix and write the right side in rank-1 form.

Setting  $X = \left(\frac{x-y}{\sqrt{2}}\right)$  and  $Y = \left(\frac{x+y}{\sqrt{2}}\right)$  then allows us to rewrite  $3x^2 - 2xy + 3y^2 = 1$  as  $4X^2 + 2Y^2 = 1$ . Setting  $Y = 0$  and  $X = 0$  gives the principal axes and square roots of  $1/2$  and  $1/4$  give the half-lengths.

This **change of basis** allows us to solve the problem easily.

Recall The Spectral Theorem says that if  $A$  is an  $n \times n$  symmetric matrix with real entries, then

- 1) the eigenvalues of  $A$  are real;
- 2) the eigenspaces are orthogonal to each other;
- 3)  $A$  is complete.

We can prove 1) and 2). The proof for 3) goes beyond the scope of this class.

Recall that if  $z = a + bi$ , then the conjugate of  $z$  is  $\bar{z} = a - bi$ , and that  $z\bar{z} = a^2 + b^2$  is a real number. Also notice that  $\overline{\bar{z}} = z$ . It is also easy to prove  $\overline{z\bar{w}} = \bar{z}w$ .

- 1) If  $A$  is symmetric and  $A\vec{x} = \lambda\vec{x}$ ,  $\vec{x} \neq \vec{0}$ , then multiplying both sides by  $\vec{x}^T$  gives

$$\vec{x}^T A\vec{x} = \lambda\vec{x}^T \vec{x}.$$

Since  $\vec{x}^T \vec{x}$  is a real number,  $\lambda$  will be real if the  $1 \times 1$  matrix product  $\vec{x}^T A\vec{x}$  is real. That will be the case if it is equal to its conjugate. Since a  $1 \times 1$  matrix product equals its transpose, we will be done if the conjugate transpose of  $\vec{x}^T A\vec{x}$  equals  $\vec{x}^T A\vec{x}$ . Show this is true.

- 2) Suppose  $\vec{x}$  and  $\vec{y}$  are eigenvectors of  $A$  with distinct eigenvalues  $\lambda_x \neq \lambda_y$  respectively. Then  $\vec{x} \in N(A - \lambda_x I)$ , but  $\vec{y}$  is not. In fact,

$$(A - \lambda_x I)\vec{y} = A\vec{y} - \lambda_x\vec{y} = (\lambda_y - \lambda_x)\vec{y} \implies \vec{y} \in C(A - \lambda_x I).$$

Since  $A - \lambda_x I$  is symmetric,  $\vec{y}$  must also be in its row space and hence orthogonal to its null space by the FTLA. Hence  $\vec{x} \cdot \vec{y} = 0$  and we are done with the proof.